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### For immediate release

### e-con Systems' new USB 3.0 Stereo vision Camera

Tara - USB 3.0 Stereo vision camera based on MT9V024 Global Shutter CMOS sensor from OnSemi; Supports Stereo WVGA(1504x480) at 60 fps over USB 3.0 in uncompressed format.

ST. LOUIS and CHENNAI, India – June 30, 2016 - e-con Systems Inc., a leading embedded camera solution company, today announced the launch of <u>Tara, a USB 3.0 Stereo vision camera</u>. Tara is based on the 1/3-inch <u>MT9V024</u>, a WVGA Global shutter monochrome CMOS image sensor from OnSemi™. The Tara supports Stereo **WVGA (1504x480) at 60fps** over USB 3.0 in uncompressed format. This Stereo vision camera provides synchronized sensor frames to the host machine over USB 3.0 interface.

Tara is bundled with a Software Development Kit (SDK) with full source code for application development on top of OpenCV, enabling customers to develop their own Stereo Vision Camera based applications. e-con Systems also provides sample applications with source code, demonstrating synchronous stereo image capture, depth measurement, disparity map and point cloud. In addition to this, customers can also develop their Stereo Vision Camera algorithms on top of Tara SDK or integrate Tara directly in their product design.



Fig: Tara - USB 3.0 Stereo Vision Camera with Pre-calibrated Lens

"I am excited with the launch of our first USB 3.0 Stereo Vision camera marking a beginning of a new camera product line for variety of applications in machine vision, autonomous driving, robotics, drones etc. With its integrated IMU, customers can determine the camera position in 3d space which is critical in these applications. e-con provides OpenCV based SDK that generates disparity map and customers can directly use these images in their applications." said Ashok Babu, President of e-con Systems Inc.

TARA with a form factor  $100 \times 30 \times 35$ mm consists of two OnSemi's 1/3 inch MT9V024 CMOS image sensors separated by an 'inter-ocular distance' or 'base line' of 60 mm and pre-calibrated lens pair mounted on S-Mount holder (Also known as M12 lens mount). The MT9V024 enhanced NIR pixel process provides excellent image quality in IR illuminated applications also. With USB





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3.0 interface to the host PC, TARA can stream uncompressed Stereo WVGA format (1504\*480) or in other words two WVGA (752x480) at 60 fps. The other resolutions supported are VGA (cropped) at 60 fps and QVGA (640\*420) at 60 fps. It also has ability to capture still images. The Tara has a 6-axis Inertial Measurement Unit (IMU) and for each frame the IMU data is transferred to the application layer. TARA is a UVC-compliant USB 3.0 Camera that is also backward compatible with USB2.0 host ports and does not require any special camera drivers to be installed in the host PC. The brightness and exposure can be controlled from the application using the standard UVC controls.



Still Image captured with digital camera



Still Image captured using Tara



**Disparity Map Raw Image** 



**Disparity Map Color Image** 

#### Tara Disparity Map sample Images

e-con provides a Software Development Kit that is built on OpenCV Image Processing Library that allows customers to get the disparity maps directly in to their application. The image capture, stereo disparity map generation etc, are done inside the SDK and customers can directly get these images in to their application using this SDK. The SDK also provides the left and right camera images separately and the customers can directly use these images for their own stereo image processing.

For customers, who want to implement their own stereo processing algorithms without using the SDK, can grab the stereo images from the camera directly using DirectShow (on Windows) or V4L2 (on Linux) APIs. With this, they can bypass the SDK and get the pixel-interleaved left and right images from the camera directly.





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e-con is also providing sample applications with source code to use with other image processing software such as MATLAB. Customers can use this sample application to develop their applications using MATLAB software.

The IMU data is sent over the USB 3.0 interface for every frame. The IMU data can be used to determine the stereo camera position in the 3d space at the time of capturing of any frame. Customers can use this IMU data along with the stereo images.

Tara, with its small form-factor design with USB 3.0 interface and accompanying SDK, is targeted for applications such as obstacle detection in autonomous driving, stock level monitoring in retail store shelves, volume measurements, robotics, proximity warning etc.

## **Availability**

Tara stereo vision USB 3.0 camera is currently available for evaluation. Customers interested in evaluating the Tara can order samples from e-con Systems' online webstore. For more information, please write to <a href="mailto:sales@e-consystems.com">sales@e-consystems.com</a>.

For more information, please visit <u>Tara - Stereo vision USB 3.0 camera</u>. Also watch Tara SDK demo video at https://www.youtube.com/watch?v=uWg3WjXOE1c

## **Customization Services**

Customers interested in customizing Tara for requirements baseline customization, sensor or optics/lens change services can contact e-con Systems directly with their requirements. e-con can also provide customized higher resolution USB stereo cameras as part of customization services. Complete customization of firmware and hardware as per customer requirements can be done. e-con Systems can also assist you in developing end stereo camera application using Tara. Please write to <a href="mailto:sales@e-consystems.com">sales@e-consystems.com</a> for any customization and additional features.

#### **About e-con Systems**

e-con Systems specializes in camera solutions with offerings like camera modules, USB camera modules, camera boards for various microprocessors, camera Device driver development services on Operating systems like Linux/Android/WinCE, Camera reference design, software ISP, camera customization services and camera tuning services.

# For more information please contact:

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